



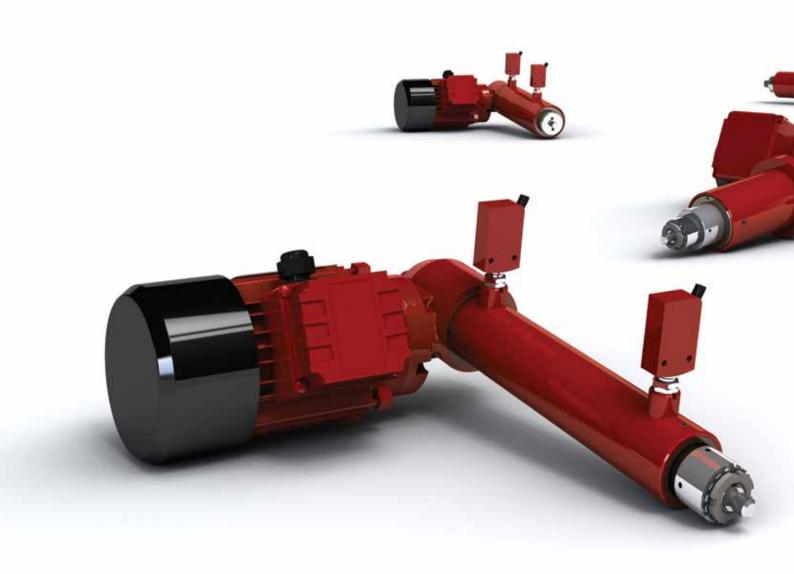
Power Jacks has a proud engineering heritage dating from the earliest years of the 20th Century. A heritage that is about excellence: about visionary design, technical expertise, robust product manufacture and customer care.

Those remain the defining characteristics of Power Jacks today as we design and build screw jacks, bevel gearboxes, linear actuators and roller screws. In fact they're more important than ever as we take our service delivery to you – the customer – to new levels of performance.

There's even more to it than that, however. We harness our engineering knowledge and capabilities not only to create a diverse linear motion product portfolio, but also to engineer individual solutions: to create customised products that help you improve your business.

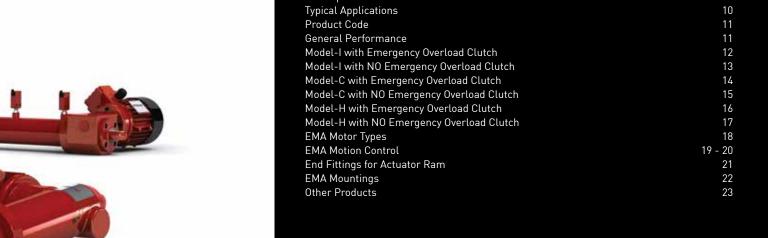
The best people, proven products, quality performance: a combination that sets us apart.

# POWER THAT'S ELECTRIC.



# **CONTENTS**

EMA Features EMA Options



#### Notes

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# OUR LINEAR ACTUATORS DELIVER POWERFUL, SMOOTH AND PRECISE LINEAR MOTION

Our EMA industrial linear actuator is designed for low to medium duty applications, with loads up to 10kN. It uses a precision spiroid gear set that delivers superior performance when compared to a similar size worm gear set.

Depending on the performance required, the gear set drives either a machine screw or ball screw to move the ram. And a wide range of options, including clutches and limit switches, are available to suit most applications.

# Overview of EMA Linear Actuator Range

#### What is EMA Linear Actuator?

EMA is an abbreviation for Electro Mechanical Actuator, which consists of either a trapezoidal or ball lead screw, driven by an electric motor through spiroid gearing. The screw converts the rotary motion into linear movement. As the screw rotates, the nut extends and retracts the ram, which is attached to the load.

#### The EMA Linear Actuator Range

There are 3 standard EMA models, all available in a right-angle drive configuration.

- Intermittent duty model (I), incorporating a trapezoidal screw
- Medium duty model (C), incorporating a ball screw
- High speed & medium duty model (H), incorporating a ball screw

Where the standard range does not meet the application specification, special actuators can be designed to meet customers' specific requirements.

## Dynamic Load Capacity and Speed

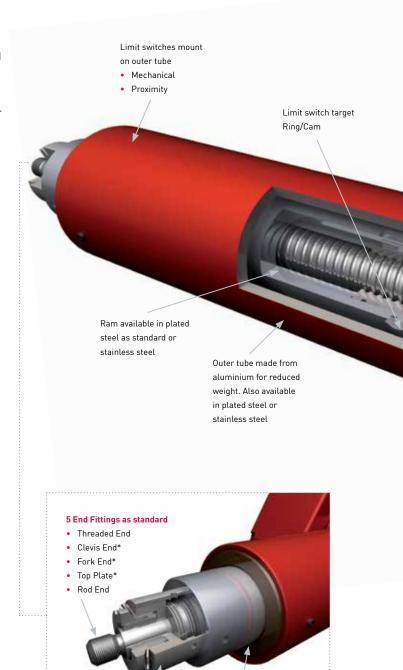
The dynamic load capacity range is up to 10 kN. A defined range of linear speeds from 135 mm/minute to 5510 mm/minute is available. The speed range is achieved by using a combination of gearbox ratios, screw leads and standard motor speeds.

#### **Drives**

As standard, the units are available with 240V/415V AC or 24V DC motors, with or without a brake. The type of motors required is dependent on the customer's application. The motors are mounted to the actuator on a 63C Face Flange Mounting.

#### Stroke

Each model can be provided with a stroke length up to the maximum shown in the Technical Charts. The stroke is defined by the customer. For a tensile load, greater maximum strokes can be accommodated, depending on the linear speed. Where the stroke required exceeds the maximum shown, or there is a high static load, please contact our Technical Sales Department.



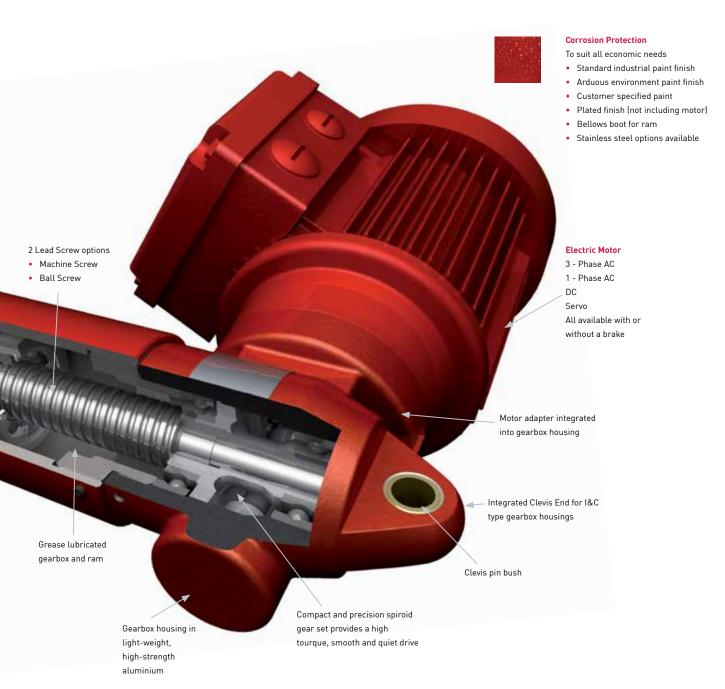
Ram sealed and

quided at end

Clutch option to limit load or

provide emergency protection

<sup>\*</sup> Zinc plated as standard stainless steel options available



#### Standard Features

- Choice of AC or DC motor drives
- Choice of end fittings: clevis, fork top plate, rod or threaded end
- Trunnion Mounting
- Limit Switches

#### **Emergency Overload Clutch**

The emergency overload clutch is a device, which is mounted on the actuator ram, which will slip when the torque to drive the load exceeds the limit set. If the load is axially locked, or if a torque greater than the clutch setting is required to move the load, the clutch will disengage the load from the ram and prevent the motor from overloading the actuator components. Please note that the clutch is an emergency device and should not be used for reversing the actuator direction.

#### **Limit Switches**

Limit switches are fitted to provide end of stroke or ultimate over travel safety. They are mounted on the outer tube of the actuator

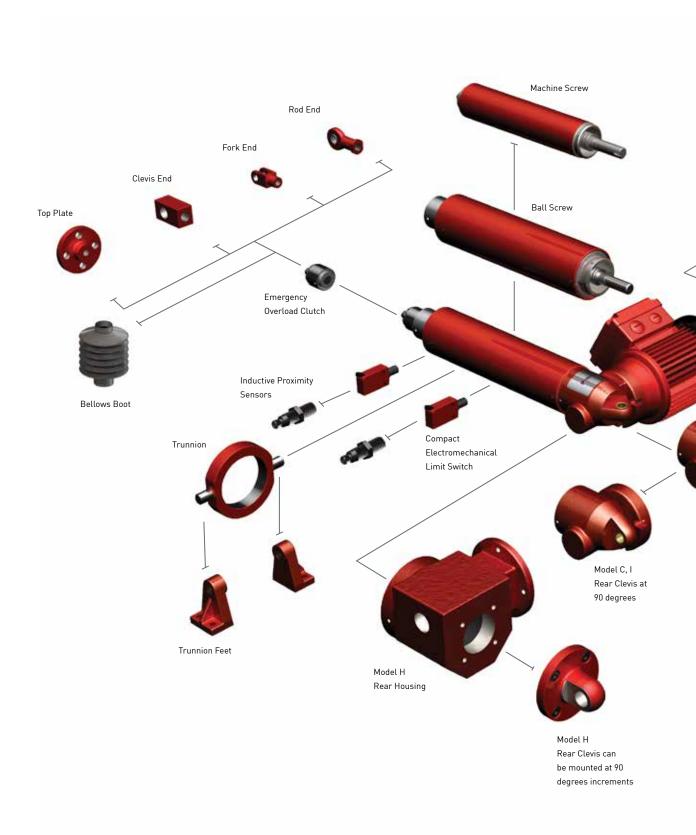
and are tripped by a collar on the ram. They are set at a fixed length defined by the customer (see dimensional page for details). Adjustable Limit Switches can be provided on request, consult Power Jacks.

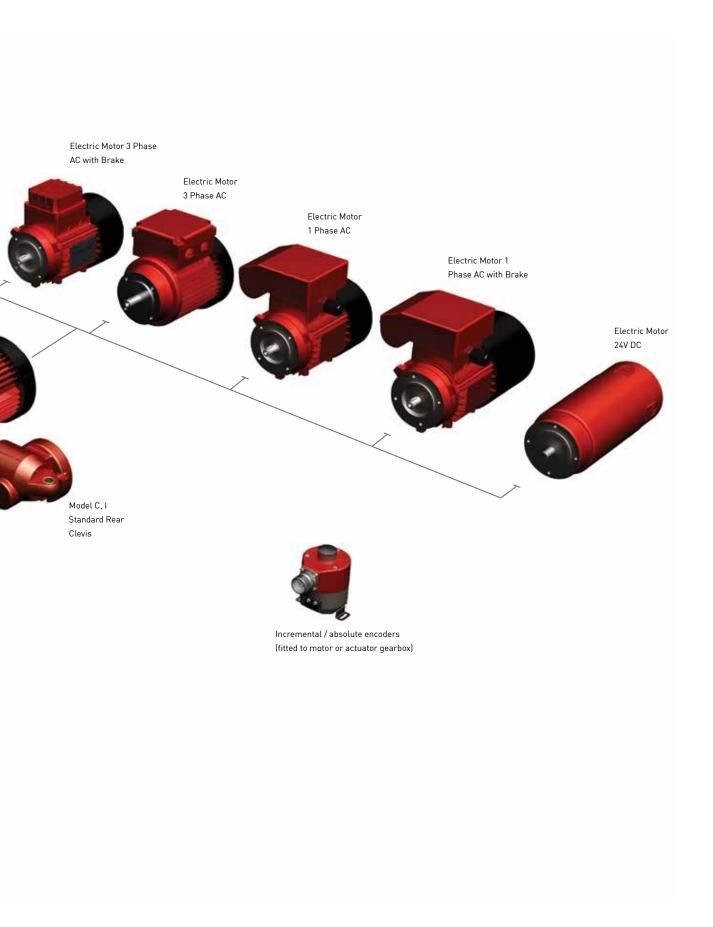
## **Guiding the Load**

Side loads on the actuator ram should be avoided by ensuring that the load is guided. The load guide mechanism should resist the torque developed at the ram by the screw mechanism. A guided ram can be supplied on request, which utilises a keyway in the inner ram, eliminates the need for torsional restraint and therefore allows flexibility in the choice of end fitting.

#### Construction

All units are constructed and finished to suit industrial operating conditions. The actuator gearbox and outer tube are painted aluminium or plated for protection and the ram is zinc plated steel. The actuator is sealed at the ram. Stainless steel options available on request.





#### Tilt/Pivot

EMA Linear Actuators can be used to tilt objects, fixed at one end, up to 180° from their starting positions. The extension and retraction of the actuator causes the object to pivot about its stationary end.

#### Lift/Lower

EMA Linear actuators can handle any lifting and lowering application up to 10kN. As the translating tube of the actuator extends and retracts, the object that the actuator is attached to is raised and lowered at a constant speed.

#### Position

When an application requires periodic adjustment to the position of an object or objects, EMA linear actuators provide the solution. The motion of the actuator allows the operator to position an object by simply pushing a button.

## Roll/Slide

When it is necessary to roll or slide an object or a mechanical assembly into position, an EMA linear actuator is the answer. The movement of the actuator causes the clamping, rolling or sliding of the desired object.

## Open/Close

An EMA linear actuator mounted on a door, gate or valve allows opening and closing operations on either a timed, or on-demand basis. As the actuator retracts the gate is opened at a steady rate; the extension of the actuator returns the gate to a closed position.

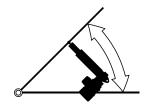
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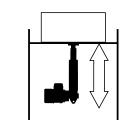
#### Tension

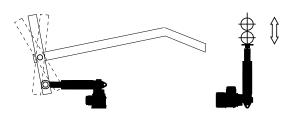
EMA linear actuators offer a perfect solution for applications in which tension on a conveyor or webb must be maintained and adjusted. An actuator mounted on a frame or roller extends and retracts to control the tension in the system.

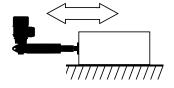
# Lock/Unlock

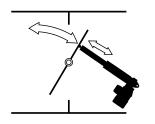
For moving a locking device such as a pin in and out of retaining slot, EMA linear actuators provides the perfect solution. The motion of the actuator allows the operator to lock and unlock the device smoothly and safely by the touch of a button. Extend and retract limit switches on the actuator can be used as lock/unlock signals for a machines control system.

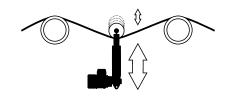


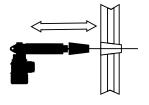












1	2	3
С	1	0

4	5	6	7
0	6	8	5

8	9	10	11	12	13
1	В	4	1	5	С

14	15	16	17
0	5	0	0

18	19	20
1	L	1

21	22	23	24
0	0	0	0



#### [1] Actuator Model

I - Intermittent Duty
C - Medium Duty

H - High Speed & Medium Duty

## [2,3] Dynamic Load Capacity

02 - 2.5kN (250 kg) 05 - 5kN (500 kg) 10 - 10kN (1000 kg)

#### [4,5,6,7] Linear Speed

This is shown as a 4-figure code refer to Technical Charts

#### [8] Gearbox Mounting

1 - Version 1 - Clevis

2 - Version 2 - Clevis 90°

3 - Version 3 - Trunnion

4 - Version 4 - Trunnion 90°

5 - Version 5 - Trunnion with feet

6 - Version 4 - Trunnion 90° with feet

The position of mounting versions 3, 4, 5, 6 is defined in characters 21, 22, 23, 24.

#### [9] Brake

0 - Non Brake Motor B - Brake Motor

#### [10,11,12] Motor Type

240 - 240V AC, 1 Phase 415 - 415V AC, 3 Phase

024 - 24V DC

XXX - Other Motor

#### [13] Ram End Fitting

C - Clevis End

F - Fork End

T - Top Plate

E - Threaded End

R - Rod End

#### [14,15,16,17] Stroke

A 4-figure code to represent the required stroke in mm

#### [18] Emergency Overload Clutch

0 - No Clutch 1 - Clutch

### [19] Limit Switches

0 - No Limit Switch

L - Mechanical Limit Switch

P - Proximity Sensor

#### [20] Limit Switch Position

- No Limit Switches

1 - Limit Switches - Position 1<sup>#1</sup>

2 - Limit Switches - Position 2

3 - Limit Switches - Position 3

- Limit Switches - Position 4

# [21,22,23, 24] Trunnion Mounting#2 Distance

A 4-figure code to represent trunnion mounting distance in mm.

100 < Distance < Stroke

#### [25] Other Feature(s)#3

0 - None

B - Bellows Boot

S - Special Design Notes

#### Notes:

#1. Standard limit position.

#2. Must be completed if trunnions selected

#3. If no character entered then there is no special feature i.e. equals "0". Design notes required to detail device/item/feature specification.

## General Performance

MODEL I (INTERMITTENT DUTY)					
Dynamic Capacity (kN)	10	5	5	5	2.5
Linear Speed (mm/min)	135	200	270	410	820
Motor Power (kW)	0.18	0.18	0.18	0.18	0.18
Motor Frame Size (IEC)	71	63	71	63	63
Motor Poles	6	4	6	2	2
Max Stroke - Compression (mm)	750	750	750	750	750
Max Stroke - Tension (mm)*	2000	2000	2000	2000	2000
Weight - no stroke (kg)			9		
Weight - per 100mm stroke (kg)			0.69		
Ambient Operating	-10°C to +50°C				
Temperature (°C)**					
Duty Cycle Rating***		, ,		i0 cycles ime per h	,

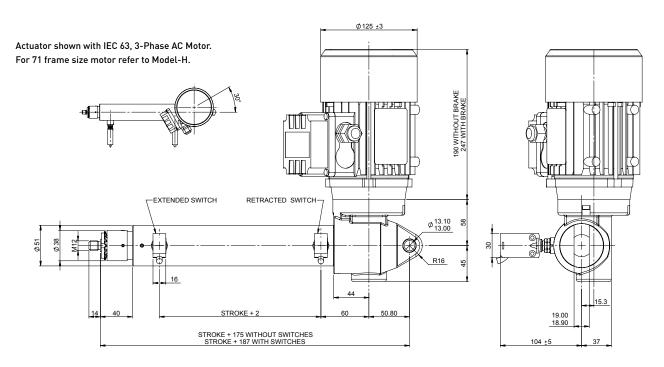
MODEL C (MEDIUM DUTY)					
Dynamic Capacity (kN)	10	10	10	5	2.5
Linear Speed (mm/min)	225	335	685	1370	2740
Motor Power (kW)	0.18	0.18	0.18	0.18	0.18
Motor Frame Size (IEC)	71	63	71	63	63
Motor Poles	6	4	2	2	2
Max Stroke - Compression (mm)	900	900	900	1250	1500
Max Stroke - Tension (mm)*	2000	2000	2000	2000	2000
Weight - no stroke (kg)			10		
Weight - per 100mm stroke (kg)	1.3				
Ambient Operating Temperature (°C)**	-10°C to +50°C				
Duty Cycle Rating***	Up to 2	0 cycles	per hour,	1000 cyc	les per

day. Up to 50% operating time per hour.

MODEL H (HIGH SPEED & MEDI	UM DUT\	7			
Dynamic Capacity (kN)	10	10	10	5	5
Linear Speed (mm/min)	900	1375	2755	1805	5510
Motor Power (kW)	0.25	0.37	0.55	0.25	0.55
Motor Frame Size (IEC)	71	71	71	71	71
Motor Poles	6	2	2	6	2
Max Stroke - Compression (mm)	900	900	900	1250	1250
Max Stroke - Tension (mm)*	2000	2000	2000	2000	2000
Weight - no stroke (kg)			12		
Weight - per 100mm stroke (kg)			1.3		
Ambient Operating Temperature (°C)**	-10°C to +50°C				
Duty Cycle Rating***	Up to 20 cycles per hour, 1000 cycles per				
	day. U	p to 50%	operating	g time pe	r hour.

#### Notes:

- Longer strokes available on request.
- \*\* Please consult Power Jacks to discuss hostile or hazardous operating environments.
- \*\*\* 1 Cycle = actuator moved to fully extended position then fully retracted position.



MODEL I (INTERMITTENT DUTY)						
Dynamic Capacity (kN)	10 5 5 5 2.5					
Linear Speed (mm/min)	135	200	270	410	820	
Motor Power (kW)	0.18	0.18	0.18	0.18	0.18	
Motor Frame Size (IEC)	71	63	71	63	63	
Motor Poles	6	4	6	2	2	
Max Stroke - Compression (mm)	750	750	750	750	750	
Max Stroke - Tension (mm)*	2000	2000	2000	2000	2000	
Weight - no stroke (kg)			9			
Weight - per 100mm stroke (kg)	0.69					
Ambient Operating Temperature (°C)**	-10°C to +50°C					
Duty Cycle Rating	Up	to 5 cycles per hour, 50	cycles per day. Up to 25	i% operating time per h	our.	

Note: \* Longer strokes available on request, \*\* Consult Power Jacks to discuss hostile or hazardous environments.

# Motor Types and Options

MOTOR TYPE						
ITEM	3 PHASE AC	1 PHASE AC	DC			
Voltage	220 - 240/380 - 415VAC	220 - 240 VAC	24VDC			
Motor Design	Induction	Single or Double Capacitor Designs	Permanent Magnet			
Frame Type	IEC, 63C Face	IEC, 63C Face	IEC, 63C Face			
Enclosure (std)	IP54	IP54	IP54			

MOTOR OPTIONS						
Brake Type	3ph AC, 1ph AC or DC	1ph AC or DC	DC			
Enclosure	IP55, 56, 65	IP55	IP55			
Encoder	Available	Available	Available			
Forced Ventilation	Available	-	Available			
Other	Inverter Rated	-	12,48 VDC			

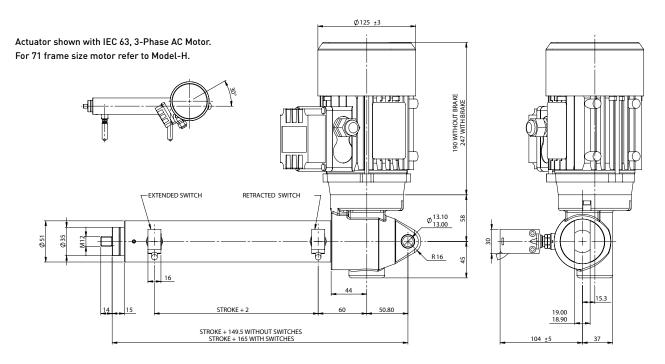
# Control Options

DEVICE	OPTION 1	OPTION 2
Limit Switches	Electro-mechanical	Inductive proximity
Clutch	Friction Clutch on Ram	-
Encoder Type	Incremental	Absolute

# Mounting Options

FITTING			
	RAM END	GEARBOX END	
Clevis	Y	Y	
Fork	Υ	N	
Threaded	Y	N	
Top Plate	Υ	N	
Trunnion	N	Y	
Rod End	Υ	N	





MODEL I (INTERMITTENT DUTY)					
Dynamic Capacity (kN)	10	5	5	5	2.5
Linear Speed (mm/min)	135	200	270	410	820
Motor Power (kW)	0.18	0.18	0.18	0.18	0.18
Motor Frame Size (IEC)	71	63	71	63	63
Motor Poles	6	4	6	2	2
Max Stroke - Compression (mm)	750	750	750	750	750
Max Stroke - Tension (mm)*	2000	2000	2000	2000	2000
Weight - no stroke (kg)			9		
Weight - per 100mm stroke (kg)	0.69				
Ambient Operating Temperature (°C)**	-10°C to +50°C				
Duty Cycle Rating	Up	to 5 cycles per hour, 50	cycles per day. Up to 25	i% operating time per h	our.

Note: \* Longer strokes available on request, \*\* Consult Power Jacks to discuss hostile or hazardous environments.

# Motor Types and Options

MOTOR TYPE			
ITEM	3 PHASE AC	1 PHASE AC	DC
Voltage	220 - 240/380 - 415VAC	220 - 240 VAC	24VDC
Motor Design	Induction	Single or Double Capacitor Designs	Permanent Magnet
Frame Type	IEC, 63C Face	IEC, 63C Face	IEC, 63C Face
Enclosure (std)	IP54	IP54	IP54

MOTOR OPTIONS			
Brake Type	3ph AC, 1ph AC or DC	1ph AC or DC	DC
Enclosure	IP55, 56, 65	IP55	IP55
Encoder	Available	Available	Available
Forced Ventilation	Available	-	Available
Other	Inverter Rated	-	12,48 VDC

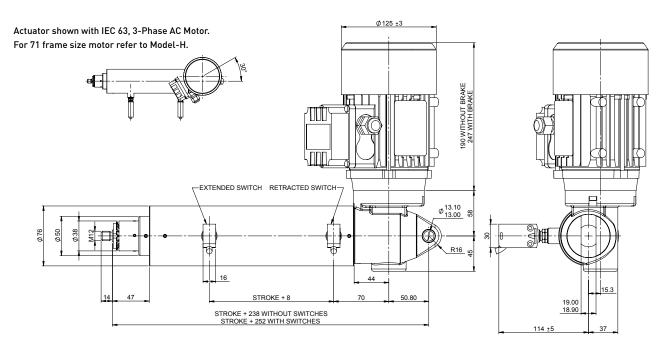
# Control Options

DEVICE	OPTION 1	OPTION 2
Limit Switches	Electro-mechanical	Inductive proximity
Clutch	Friction Clutch on Ram	-
Encoder Type	Incremental	Absolute

# **Mounting Options**

FITTING				
	RAM END	GEARBOX END		
Clevis	Υ	Υ		
Fork	Y	N		
Threaded	Υ	N		
Top Plate	Y	N		
Trunnion	N	Υ		
Rod End	Υ	N		





MODEL C (MEDIUM DUTY)					
Dynamic Capacity (kN)	10	10	10	5	2.5
Linear Speed (mm/min)	225	335	685	1370	2740
Motor Power (kW)	0.18	0.18	0.18	0.18	0.18
Motor Frame Size (IEC)	71	63	71	63	63
Motor Poles	6	4	2	2	2
Max Stroke - Compression (mm)	900	900	900	1250	1500
Max Stroke - Tension (mm)*	2000	2000	2000	2000	2000
Weight - no stroke (kg)			10		
Weight - per 100mm stroke (kg)	1.3				
Ambient Operating Temperature (°C)**	-10°C to +50°C				
Duty Cycle Rating	Up to	20 cycles per hour, 100	00 cycles per day. Up to	50% operating time per	hour.

Note: \* Longer strokes available on request, \*\* Consult Power Jacks to discuss hostile or hazardous environments.

# Motor Types and Options

MOTOR TYPE				
ITEM	3 PHASE AC	1 PHASE AC	DC	
Voltage	220 - 240/380 - 415VAC	220 - 240 VAC	24VDC	
Motor Design	Induction	Single or Double Capacitor Designs	Permanent Magnet	
Frame Type	IEC, 63C Face	IEC, 63C Face	IEC, 63C Face	
Enclosure (std)	IP54	IP54	IP54	

MOTOR OPTIONS				
Brake Type	3ph AC, 1ph AC or DC	1ph AC or DC	DC	
Enclosure	IP55, 56, 65	IP55	IP55	
Encoder	Available	Available	Available	
Forced Ventilation	Available	-	Available	
Other	Inverter Rated	-	12,48 VDC	

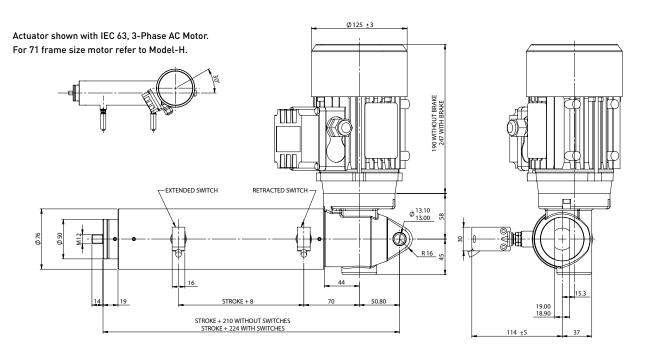
# Control Options

DEVICE	OPTION 1	OPTION 2
Limit Switches	Electro-mechanical	Inductive proximity
Clutch	Friction Clutch on Ram	-
Encoder Type	Incremental	Absolute

# Mounting Options

FITTING			
	RAM END	GEARBOX END	
Clevis	Y	Y	
Fork	Υ	N	
Threaded	Y	N	
Top Plate	Υ	N	
Trunnion	N	Y	
Rod End	Υ	N	





MODEL C (MEDIUM DUTY)						
Dynamic Capacity (kN)	10	10	10	5	2.5	
Linear Speed (mm/min)	225	335	685	1370	2740	
Motor Power (kW)	0.18	0.18	0.18	0.18	0.18	
Motor Frame Size (IEC)	71 63 71 63 63					
Motor Poles	6	4	2	2	2	
Max Stroke - Compression (mm)	900	900	900	1250	1500	
Max Stroke - Tension (mm)*	2000	2000	2000	2000	2000	
Weight - no stroke (kg)			10			
Weight - per 100mm stroke (kg)	1.3					
Ambient Operating Temperature (°C)**	-10°C to +50°C					
Duty Cycle Rating	Up to	20 cycles per hour, 100	00 cycles per day. Up to	50% operating time per	hour.	

Note: \* Longer strokes available on request, \*\* Consult Power Jacks to discuss hostile or hazardous environments.

# Motor Types and Options

MOTOR TYPE					
ITEM	3 PHASE AC	1 PHASE AC	DC		
Voltage	220 - 240/380 - 415VAC	220 - 240 VAC	24VDC		
Motor Design	Induction	Single or Double Capacitor Designs	Permanent Magnet		
Frame Type	IEC, 63C Face	IEC, 63C Face	IEC, 63C Face		
Enclosure (std)	IP54	IP54	IP54		

MOTOR OPTIONS						
Brake Type	3ph AC, 1ph AC or DC	1ph AC or DC	DC			
Enclosure	IP55, 56, 65	IP55	IP55			
Encoder	Available	Available	Available			
Forced Ventilation	Available	-	Available			
Other	Inverter Rated	-	12,48 VDC			

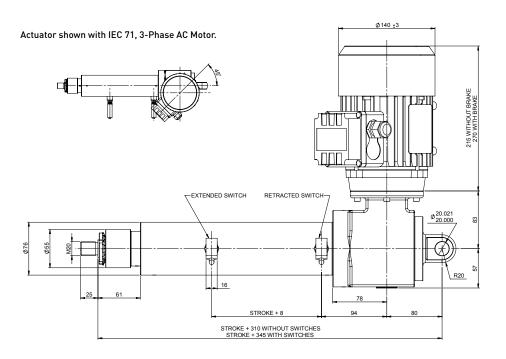
# Control Options

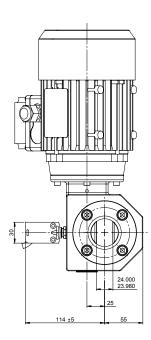
DEVICE	OPTION 1	OPTION 2
Limit Switches	Electro-mechanical	Inductive proximity
Clutch	Friction Clutch on Ram	-
Encoder Type	Incremental	Absolute

# **Mounting Options**

FITTING					
	RAM END	GEARBOX END			
Clevis	Y	Υ			
Fork	Υ	N			
Threaded	Υ	N			
Top Plate	Υ	N			
Trunnion	N	Y			
Rod End	Υ	N			







MODEL H (HIGH SPEED & MEDIUM DUTY)							
Dynamic Capacity (kN)	10	10 10 10 5 5					
Linear Speed (mm/min)	900	1375	2755	1805	5510		
Motor Power (kW)	0.25	0.37	0.55	0.25	0.55		
Motor Frame Size (IEC)	71 71 71 71 71						
Motor Poles	6	2	2	6	2		
Max Stroke - Compression (mm)	900	900	900	1250	1250		
Max Stroke - Tension (mm)*	2000	2000	2000	2000	2000		
Weight - no stroke (kg)	12						
Weight - per 100mm stroke (kg)	1.3						
Ambient Operating Temperature (°C)**	-10°C to +50°C						
Duty Cycle Rating	Up to	20 cycles per hour, 100	00 cycles per day. Up to	50% operating time per	hour.		

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# Motor Types and Options

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Motor Design	Induction	Single or Double Capacitor Designs	Permanent Magnet		
Frame Type	IEC, 63C Face	IEC, 63C Face	IEC, 63C Face		
Enclosure (std)	IP54	IP54	IP54		

MOTOR OPTIONS						
Brake Type	3ph AC, 1ph AC or DC	1ph AC or DC	DC			
Enclosure	IP55, 56, 65	IP55	IP55			
Encoder	Available	Available	Available			
Forced Ventilation	Available	-	Available			
Other	Inverter Rated	-	12,48 VDC			

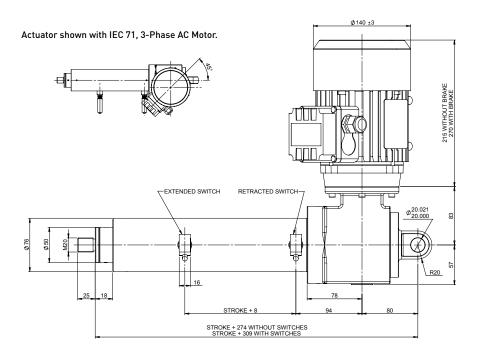
# **Control Options**

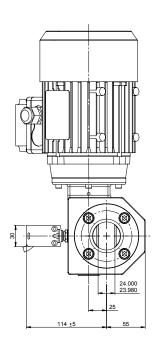
DEVICE	OPTION 1	OPTION 2
Limit Switches	Electro-mechanical	Inductive proximity
Clutch	Friction Clutch on Ram	-
Encoder Type	Incremental	Absolute

# **Mounting Options**

FITTING					
	RAM END	GEARBOX END			
Clevis	Y	Y			
Fork	Y	N			
Threaded	Y	N			
Top Plate	Y	N			
Trunnion	N	Y			
Rod End	Υ	N			







MODEL H (HIGH SPEED & MEDIUM DUTY)					
Dynamic Capacity (kN)	10	10	10	5	5
Linear Speed (mm/min)	900	1375	2755	1805	5510
Motor Power (kW)	0.25	0.37	0.55	0.25	0.55
Motor Frame Size (IEC)	71	71	71	71	71
Motor Poles	6	2	2	6	2
Max Stroke - Compression (mm)	900	900	900	1250	1250
Max Stroke - Tension (mm)*	2000	2000	2000	2000	2000
Weight - no stroke (kg)			12		
Weight - per 100mm stroke (kg)	1.3				
Ambient Operating Temperature (°C)**	-10°C to +50°C				
Duty Cycle Rating	Up to	20 cycles per hour, 100	00 cycles per day. Up to	50% operating time per	hour.

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# Motor Types and Options

MOTOR TYPE					
ITEM	3 PHASE AC	1 PHASE AC	DC		
Voltage	220 - 240/380 - 415VAC	220 - 240 VAC	24VDC		
Motor Design	Induction	Single or Double Capacitor Designs	Permanent Magnet		
Frame Type	IEC, 63C Face	IEC, 63C Face	IEC, 63C Face		
Enclosure (std)	IP54	IP54	IP54		

	MOTOR OPTIONS				
Brake Type	3ph AC, 1ph AC or DC	1ph AC or DC	DC		
Enclosure	IP55, 56, 65	IP55	IP55		
Encoder	Available	Available	Available		
Forced Ventilation	Available	-	Available		
Other	Inverter Rated	-	12,48 VDC		

# Control Options

DEVICE	OPTION 1	OPTION 2
Limit Switches	Electro-mechanical	Inductive proximity
Clutch	Friction Clutch on Ram	-
Encoder Type	Incremental	Absolute

# **Mounting Options**

FITTING				
	RAM END	GEARBOX END		
Clevis	Y	Υ		
Fork	Υ	N		
Threaded	Υ	N		
Top Plate	Υ	N		
Trunnion	N	Y		
Rod End	Y	N		

## Related Accessories



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# **Motor Types**

As standard, the units are available with 240V/415VAC 3-phase or 240VAC 1-phase or 24VDC motors, with or without a brake. The type of motors required is dependent on the customer's application. The motors are mounted to the actuator on an IEC 63C B14 Face Mounting.

MOTOR TYPE				
ITEM	3 PHASE	1 PHASE	DC	
Voltage	220 - 240/380 - 415VAC	220 - 240 VAC	24VDC	
Motor Design	Induction	Single or Double Capacitor Designs	Permanent Magnet	
Frame Type	IEC (NEMA on request)	IEC (NEMA on request)	IEC (NEMA on request)	
Enclosure (std)	IP54	IP54	IP54	

Brake	3ph AC, 1ph AC or DC	1ph AC or DC	DC
Enclosure	IP55, 56, 65	IP55	IP55
Encoder	Available	Available	Available
Forced Ventilation	Available	-	Available
Other	Inverter Rated	-	12,48 VDC



#### Standard 3-phase

Key Features
3 Phase, 50 Hz / 60Hz
220-240/380-415VAC
B14 Face Mounting
2-Pole (3000 rpm), 4-Pole (1500 rpm),
6-Pole (1000 rpm)
IEC Frame Sizes to 63-71

#### Standard 3-phase with brake

Key Features
3 Phase, 50 Hz / 60Hz
220-240/380-415VAC
B14 Face Mounting
2-Pole (3000 rpm), 4-Pole (1500 rpm),
6-Pole (1000 rpm)
IEC Frame Sizes 63 to 71
High torque DC brake
rectifier: 230VAC, 50/60Hz
(others on request)

#### **Benefits**

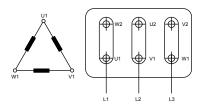
High efficiency – low running costs Low noise levels High power factors

- High torque with smooth acceleration and low current
- Multi-mount versatility for mounting arrangement and terminal box position
- Aluminium construction for light weight and corrosion resistance
- Four position cable entry

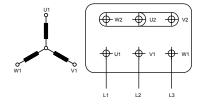
# Wiring Diagram

3-Phase Motor Wiring Diagram (Example-always check for exact motor used)

#### **Delta** connection



#### Star connection

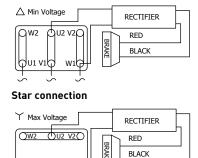


3-Phase Braked Motor Wiring Diagram (Example-always check for exact motor used)

For brake motors with dc brake required at 230/400V 50Hz, the rectifier is directly connected to the motor terminal block as follows.

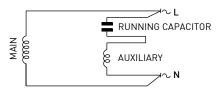
If using an inverter (frequency converter) then the brake must use a separate power supply to the rectifier.

#### Delta connection

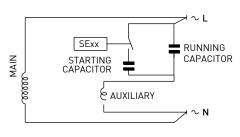


1-Phase Motor Wiring Diagram (Example-always check for exact motor used)

## Single Capacitor



## **Double Capacitor**



#### Standard EMA Actuator Limit Switch

Our range of motion control devices allows you to safe guard the operation of you actuator system and ensures it operates within the specified parameters.

#### **Standard Limit Switches**

- Electro-Mechanical Switches
- Proximity Sensors (Inductive)
- Safety Rated Limit Switches
- · Compact reduced height designs
- Threaded Barrel Mounting
- Flying cable or plug-in connector options
- Enclosures up to IP65 IP67 available

#### Non Standard Limit Switches

- Other limit switches can be supplied to suit most applications.
- Different sizes, shape design and enclosure electro-mechanical limit switches
- Capacitive proximity sensor
- · Bolt on Limit Switches
- Hazardous Area Rated electro-mechanical limit switch
- High or low temperature rated
- Enclosures up to IP68 available

For further details, consult Power Jacks



View A

Showing Limit

Switches Position 1

**Proximity Sensor** 

# Electro-Mechanical Switch Specifications

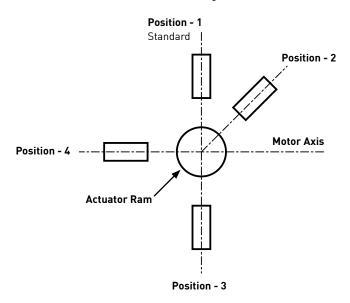
Housing	Metal, compact housing, totally enclosed and sealed
Pre-cabled	2m PVC cable 5 x 0.75mm2 (other cable lengths available on request)
Switch type	Single pole, 1 change-over, snap action
Max actuation speed	0.5 m/s
Mechanical durability	10 million operating cycles
Operation	-25°C +77°C
Storage	-40°C +70°C
Product conformity	IEC947-5-1
Enclosure	IP67
Operating	AC - 15; B300 (UE = 240V, le = 1.5A)
characteristics	DC - 13; R300 (UE = 240V, le = 0.1A)
Insulation voltage	Ui = 300V

#### Notes:

- As standard 2 limit switches are mounted for end of travel positions. These switches are mounted in the same position radially on the actuators ram.
- More than 2 limit switches can be installed and limit switches can be individually mounted at different radial positions.
- Alternative switch mounting positions along the actuators ram are available on request.

#### View A

Alternative Limit Switch Mounting Orientations



Encoders are mounted to an EMA Actuator either on the back of an electric motor (under cowling) or on the actuators gearbox opposite the motor.

#### Absolute Encoders

- Hollow or Solid shaft designs
- Multi-Turn
- SSI, 25-Bit, RS422
- Configurable interface
- Resolution up to 8192 steps x 8192 revolutions
- Enclosure Up to IP66 as standard

Other designs available on request

#### Incremental Encoders

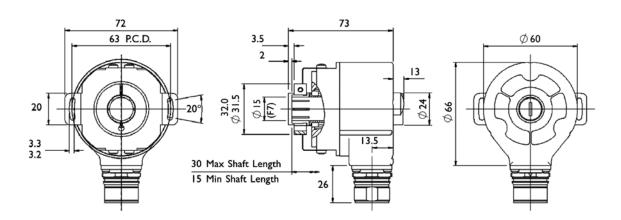
- Hollow or Solid shaft designs
- Multi-Turn
- Signal lines from 1 to 8192
- RS422 or Push-pull output drivers
- Enclosure Up to IP66 as standard

Other designs available on request

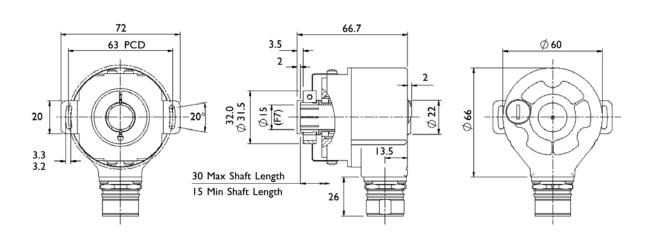


**Absolute** 

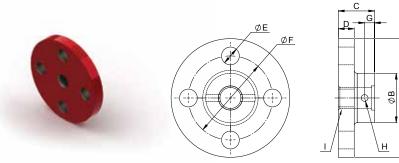
### **Absolute**



#### Incremental



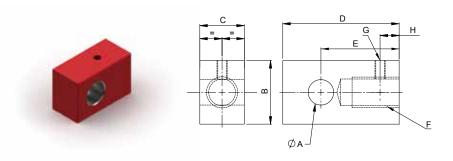
# Top Plate



MODEL	I	С	Н
ØA	Ø80	Ø80	Ø100
ØВ	Ø30	Ø30	Ø40
С	24	24	31.5
D	10	10	12
ØE	Ø11	Ø11	Ø13.5
ØF (PCD)	Ø55	Ø55	Ø70
G	8	8	10
Н	M6 x 1	M6 x 1	M8 x 1.25
I	M12 x 1.75	M12 x 1.75	M20 x 2.5
Weight (kg)	0.43	0.43	0.79

PCD = Pitch Circle Diameter.

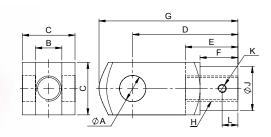
# Clevis End



MODEL	T	С	Н
ØA	Ø13	Ø13	Ø20
В	25	25	35
С	19	19	30
D	39	39	65
E	26	26	41
F	M12 x 1.75	M12 x 1.75	M20 x 2.5
	16 Deep	16 Deep	27 Deep
G	M5 x 0.8	M5 x 0.8	M6 x 1
Н	15	15	15
Weight (kg)	0.2	0.2	0.5

# Fork

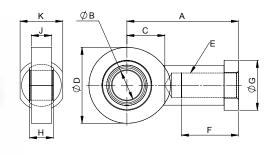




MODEL	l l	С	Н
ØA	Ø12	Ø12	Ø20
В	12	12	20
С	24	24	40
D	48	48	80
Е	24	24	40
F	18	18	30
G	62	62	105
Н	M12 x 1.75	M12 x 1.75	M20 x 2.5
Ø٦	20	20	34
K	M6 x 1	M6 x 1	M8 x 1.25
L	10	10	10
Weight (kg)	0.12	0.12	0.55

# Rod End





MODEL	- 1	С	Н
Α	50	50	77
ØB	12	12	20
С	18	18	27
ØD	34	34	53
E	M12 x 1.75	M12 x 1.75	M20 x 1.5
F	23	23	40
ØG	22	22	35
Н	10	10	16
J	8	8	13
K	19	19	32
Weight (kg)	0.096	0.096	0.35

#### Note:

Lead screw threaded end made to suit rod end.

# Mounting

There are two possible ways of mounting the EMA actuator at the gearbox end. By means of bearing journals for trunnion mounting or clevis mount.

Special mounting arrangements available on request e.g. flange on outer tube of ram, or clamp point on ram.

#### The Ram

A threaded end is standard on all models.

Attachments are threaded on to the end of the ram and locked in place.

The actuator can then be attached to the customers structure by a pinned or bolted connection depending on chosen model.

### Rear Clevis

Mount the actuator by attaching the desired bracket and pin to the clevis end. Verify that the ram attachment is aligned throughout the actuator stroke before connecting the ram. The ram attachment will either be pinned or bolted in place depending on chosen model.

## **Trunnion Mount**

Mount the actuator by attaching the desired bearings (or mounting feet) to the trunnion pins. Verify that the ram attachment is aligned throughout the actuator stroke before connecting the ram.

#### **Trunnion Mount Note:**

The position of mounting versions 3 and 4 is variable and should be specified by the customer at the time of ordering. (Dimension X). Also refer product code - "Trunnion Mounting Distance"

MODEL	I	С	Н
ØS	11.99	14.99	14.99
	11.96	14.96	14.96
Т	70	100	100
U	110	140	140

Mounting positions 5 and 6 are the same as 3 and 4 except they include trunnion feet.

#### Important Note:

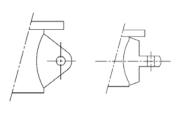
Always ensure that clevis holes align correctly and that they allow for the correct angle of pivoting for the application before operating the actuator.

#### Important Note:

Side loads on the actuator ram should be avoided by ensuring that the load is guided. The load guide mechanism should resist the torque developed at the ram by the screw mechanism. A guided ram can be supplied on request, which utilises a keyway in the inner ram, eliminates the need for torsional restraint and therefore allows flexibility in the choice of end fitting. The desired mounting orientation will be determined when placing the order; this orientation must be maintained at installation.

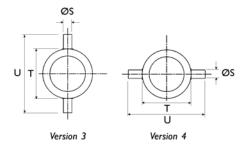


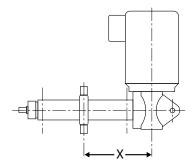




Version I

Version 2





Actuator shown with trunnion mount version-3 and rear clevis version-1.











# Single Face Screw Jacks

- Metric Machine Screw Jacks 5kN to 2000kN
- Metric Ball Screw Jacks 10kN to 500kN
- Metric Stainless Steel Screw Jacks 10kN to 300kN
- Imperial (inch) Machine Screw Jacks 1/4Ton to 250Ton
- Imperial (inch) Ball Screw Jacks 1/2Ton to 50Ton
- Imperial (inch) Stainless Steel Screw Jacks 2Ton to 100Ton
- Special Designs Available Up To 3500kN

#### **EMA Linear Actuators**

- Machine Screw & Ball Screw
- Low load, Medium Duty, High Speed
- Dynamic Load Ratings up to 10kN
- Linear Speeds up to 5500 mm/min
- 3-phase AC, 1-phase AC, and DC types
- Special Designs Available

## Rolaram Linear Actuators

- Ball Screw & Roller Screw
- High load, High Duty, High Speed
- Very High Accuracy
- Dynamic Load Ratings up to 400kN
- Linear Speeds up to 7000 mm/min
- 3-phase AC, 1-phase AC, and DC types
- True continuous duty / cycling actuator designs available
- Special Designs Available

## Spiracon Roller Screws

- High Dynamic Loads up to 1200kN
- High Efficiency
- High Positional Accuracy
- Long Life
- Low Maintenance
- Low Noise
- Robust Design for Harsh Environments
- Special Designs Available

#### Neeter Drive Bevel Gearboxes

- 2-way, 3-way and 4-way Designs
- Solid Shaft & Hollow Shaft
- Motor Adaptors
- Gear Ratios 1:1, 1.5:1, 2:1, 3:1 and 4:1
- Torque Ratings up to 3000Nm
- Special Gear Ratios and Designs Available

PRECISION SCREW JACKS . ELECTRIC LINEAR ACTUATORS . PLANETARY ROLLER SCREW . SPIRAL BEVEL GEARBOXES .

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Power Jacks Ltd Balmacassie Commercial Park Ellon, AB41 8BX Scotland (UK)

Tel: +44 (0)1358 285100 sales@powerjacks.com

#### www.powerjacks.com

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